

Application manual Programming ABB RPC S-series Integrated Power Source

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Application manual Programming ABB RPC S-series Integrated Power Source

RobotWare 6.0

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Overview of this manual

About this manual

This manual contains information on how to:

- · Create and operate jobs.
- · Edit parameters.
- Read power source information and execute advanced functions.
- Backup and restore of XML files.

Usage

This manual is intended to be used for:

- Programming
- Maintenance

Who should read this manual?

This manual is intended for:

- Robot programmers
- · Maintenance personnel

Prerequisites

The reader must be familiar with:

- · Industrial robots and the relevant terminology.
- · System parameters and how to configure them.

References

Reference	Document ID
Application manual - Arc and Arc Sensor	3HAC050988-001
Introduction and Safety - Arc Welding Products	3HAC050981-001
Technical reference manual - System parameters	3HAC050948-001
Technical reference manual - RAPID Instructions, Functions and Data types	3HAC050917-001

Revisions

Revision	Description
-	Released with RobotWare 6.0.



1 Safety

1.1 Safety

Safety of personnel

A robot is heavy and extremely powerful regardless of its speed. A pause or long stop in movement can be followed by a fast hazardous movement. Even if a pattern of movement is predicted, a change in operation can be triggered by an external signal resulting in an unexpected movement.

Therefore, it is important that all safety regulations are followed when entering safeguarded space.

Safety regulations

Before beginning work with the robot, make sure you are familiar with the safety regulations described in the manual *Operating manual - General safety information*.

1.2 Safety for arc welding

1.2 Safety for arc welding

Safety instructions for arc welding

Safety instructions can be found in the manual *Introduction and Safety - Arc Welding Products* for all steps that involve risk of personal injury or material damage. In addition, they are included in the instructions for each step.

General warnings, where the intention is to avoid problems, are only included in the instructions.



WARNING

All personnel working with the welding robot system must have a full understanding of the applicable safety instructions.

2 Integrated Power Source application

2.1 Overview

Supported power sources

Integrated Power Source is an administrative interface for power sources in the FlexPendant. The following power sources are compatible with the Integrated Power Source:

- · RPC Synergic 300
- RPC Synergic 400
- RPC Synergic 500

Firmware requirements

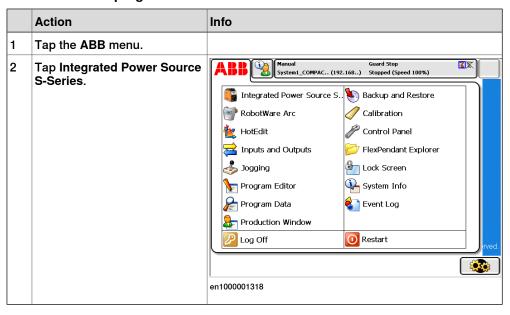
Integrated Power Source can only work with the power source of required firmware:

- · Panel version: 5A8 or later
- · Robot Interface version: 9A7 or later

2.2 Starting Integrated Power Source

2.2 Starting Integrated Power Source

Starting the Integrated Power Source program tool



Integrated Power Source start window

Once the program is loaded, the start window of Integrated Power Source is displayed (a desktop with icons). The power source functions can be accessed from this window.



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2.3 Active arc welding system

2.3 Active arc welding system

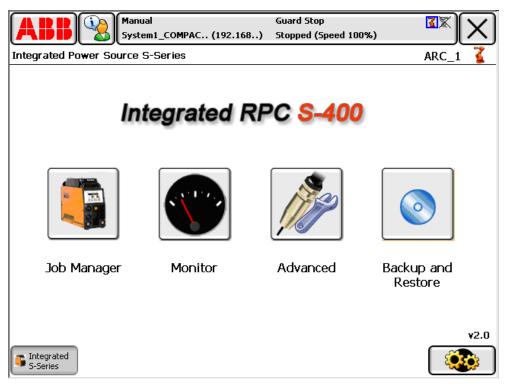
General

The selection of the AW system determines which equipment is active when manual operations (Gas On, Manual Wire feed, Editing jobs) are executed.

For information on how to change active arc welding system, see *Selecting arc* welding system on page 23.

Active power source information

The name of the active arc welding system is indicated in the upper right-hand corner. The Integrated Power Source supports up to four robots and each robot can have one RPC S-Series power source.



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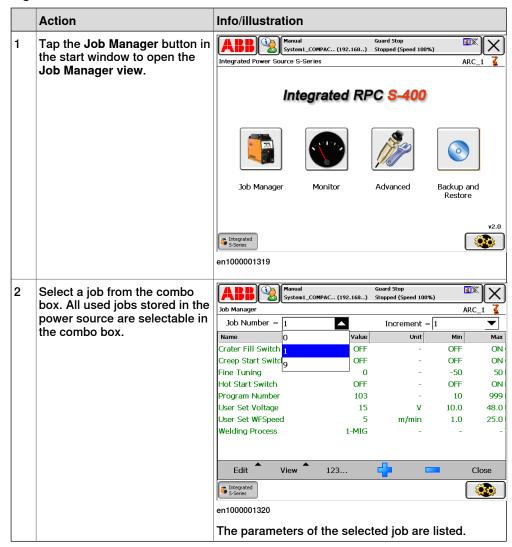


3 Integrated Power Source application details

3.1 Job Manager

3.1.1 The Job Manager view

Opening the Job Manager view



Refreshing the job parameters



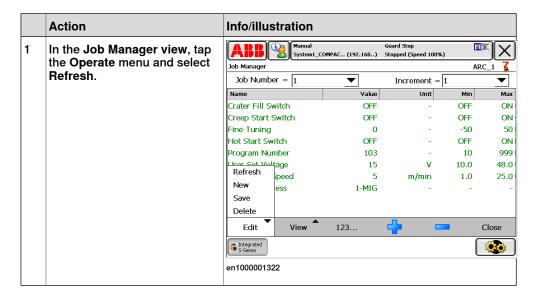
Note

All modifications of the job are lost when refreshing. To preserve the modifications, save the job.

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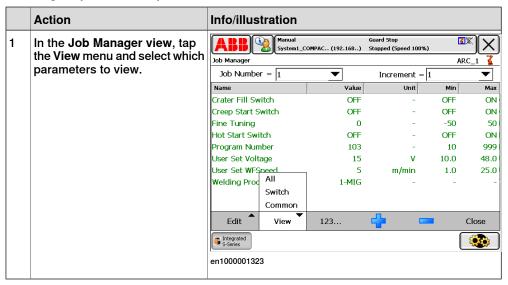
3.1.1 The Job Manager view

Continued



Filter the job parameters

It is possible to filter the parameter list, showing only the common parameters or showing only the switch parameters.



3.1.2 Handling jobs

3.1.2 Handling jobs

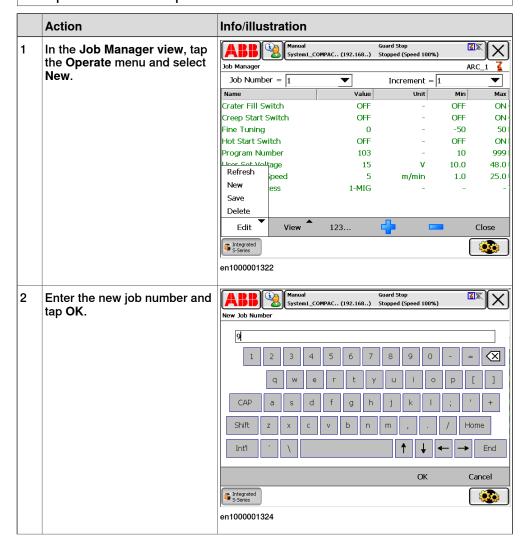
Creating a new job



Note

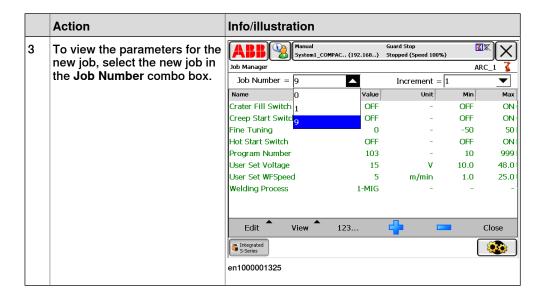
A new job number should be numeric from 0 to 89.

If the new job number is the same as one of the used job numbers, the job will be replaced with default parameters.



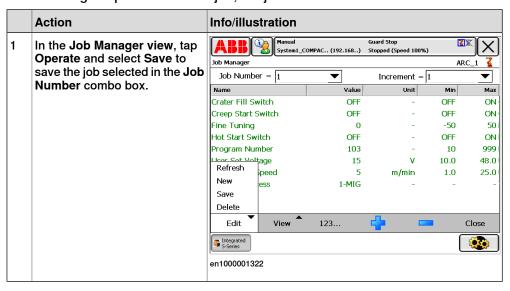
3.1.2 Handling jobs

Continued



Saving a job

When editing the parameters of a job, the job needs to be saved.

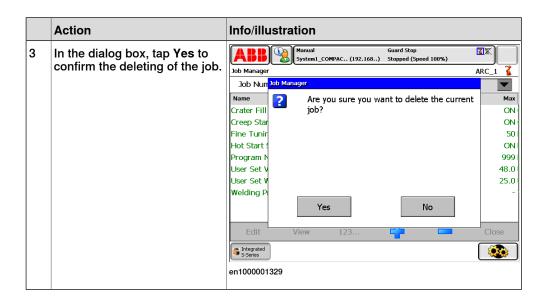


Deleting a job

	Action	Info/illustration
1	In the Job Manager view , select the job number in the Job Number combo box.	
2	Tap Operate and select Delete.	

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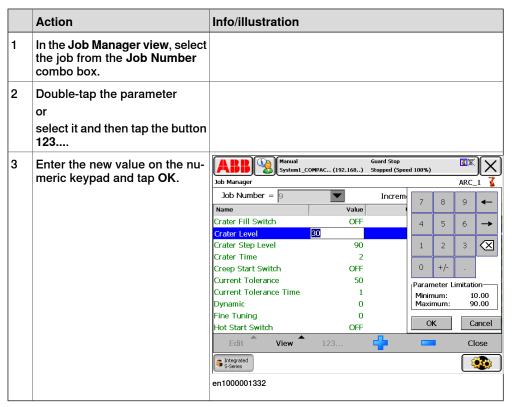
3.1.2 Handling jobs Continued



3.1.3 Editing job parameters

3.1.3 Editing job parameters

Editing parameter values



Editing job number

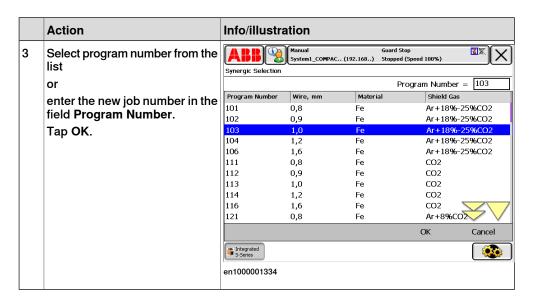


Note

All the modifications of the job are lost when changing the job number. To preserve the modifications, save the job.

	Action	Info/illustration
1	In the Job Manager view , select the job from the Job Number combo box.	
2	Double-tap the parameter (or select it and then tap the button 123).	

3.1.3 Editing job parameters Continued



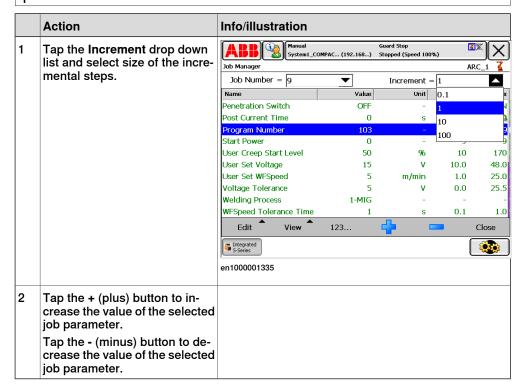
Incremental changes of parameter values

The parameter values can easily be increased or decreased in incremental steps.



Note

Switch parameters can only have value 0 or 1. The increment size for these parameters must therefore be 1.

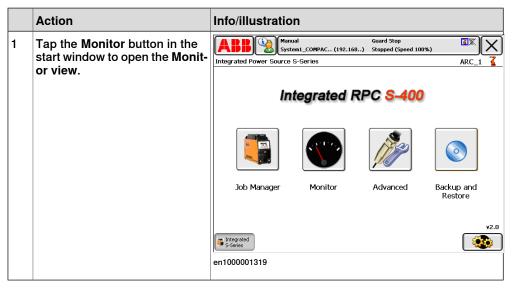


3.2.1 The Monitor view

3.2 Monitor

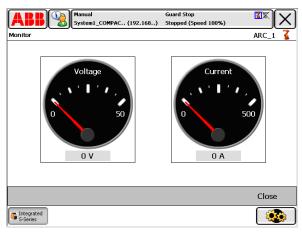
3.2.1 The Monitor view

Opening the Monitor view



About the Monitor view

The **Monitor view** displays one voltage meter and one current meter. They show values that are measured and returned by the power source.



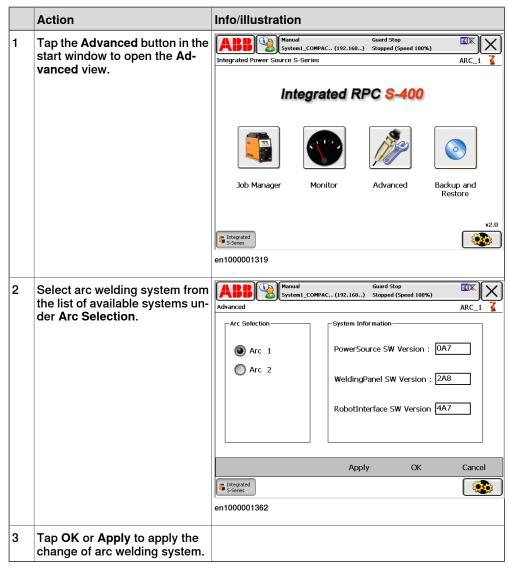
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3.3.1 The Advanced view

3.3 Advanced

3.3.1 The Advanced view

Selecting arc welding system



3.4.1 The backup and restore function

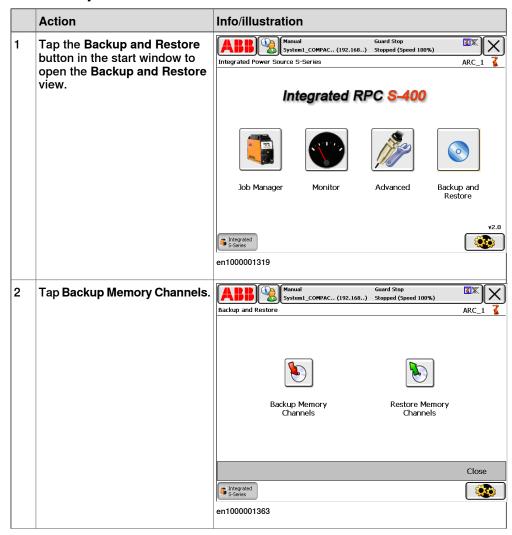
3.4 Backup and Restore

3.4.1 The backup and restore function

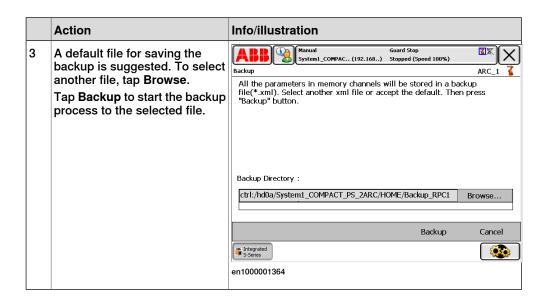
About backup and restore

The backup and restore function is used to back up the parameters of all the used jobs in a specified XML file and to restore all the jobs from a specified XML file.

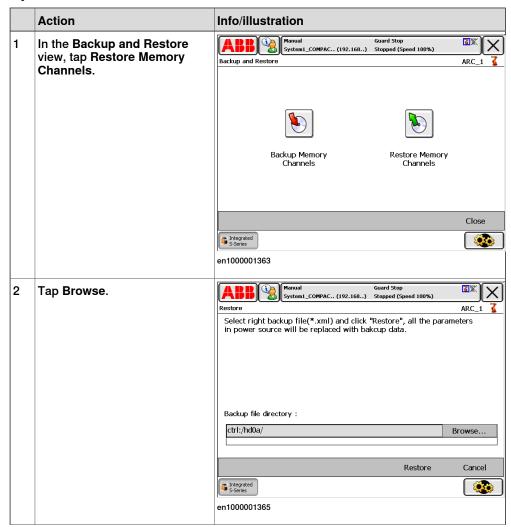
Creating a backup of the current jobs



3.4.1 The backup and restore function *Continued*



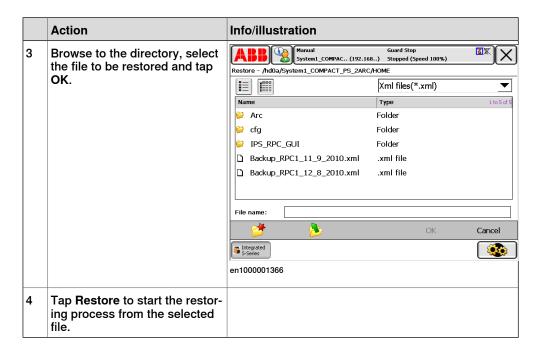
Restoring a backup of jobs



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3.4.1 The backup and restore function

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